

The Status and Performance of the CMS Pixel Detector

Souvik Das
Cornell University

on behalf of the CMS Pixels team

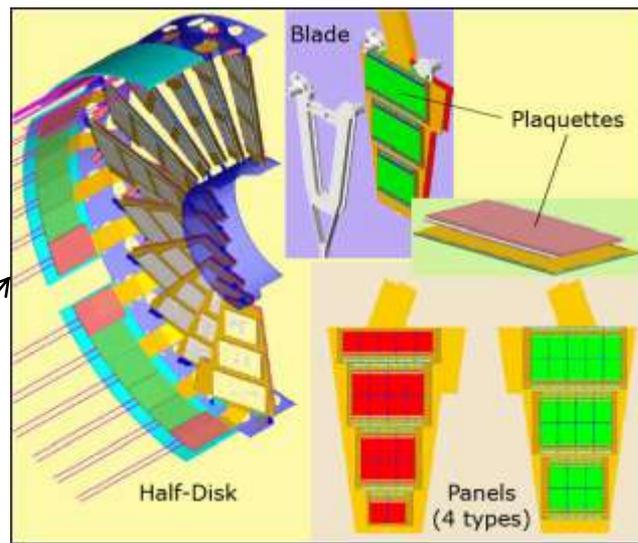
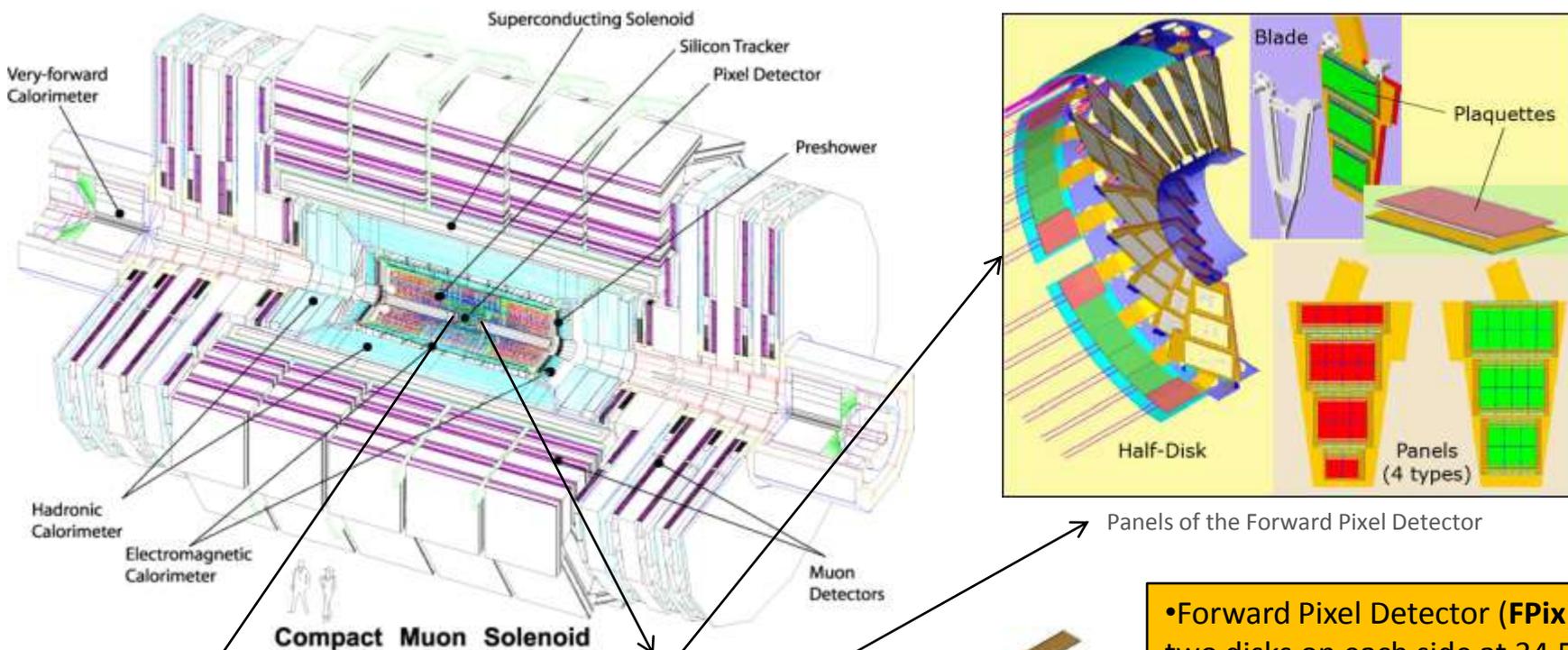
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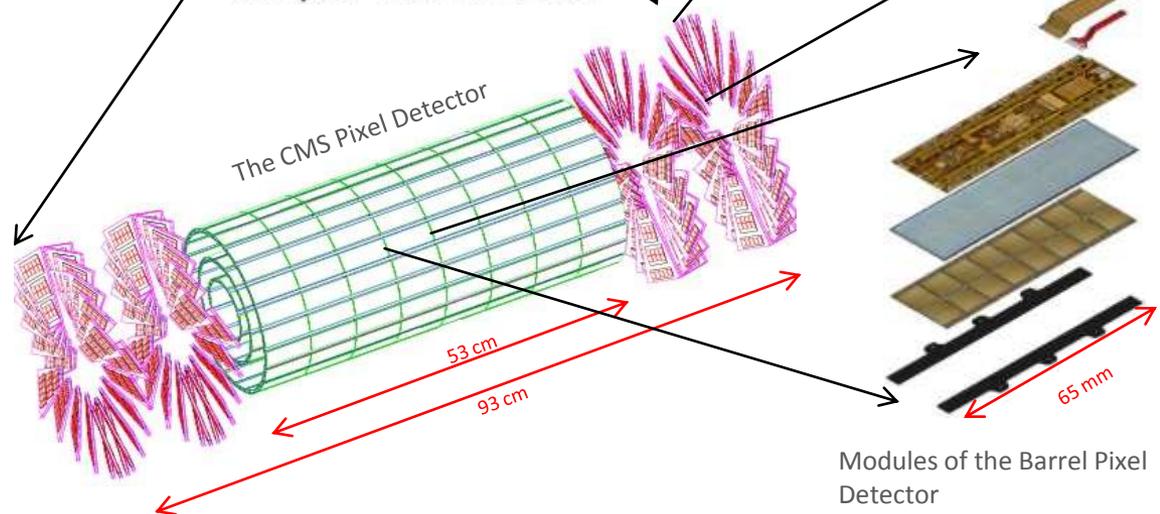
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The Pixel Detector in the Compact Muon Solenoid



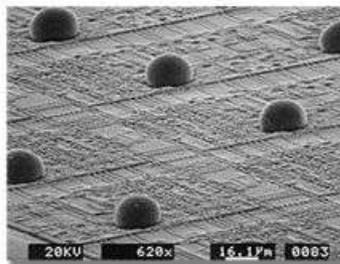
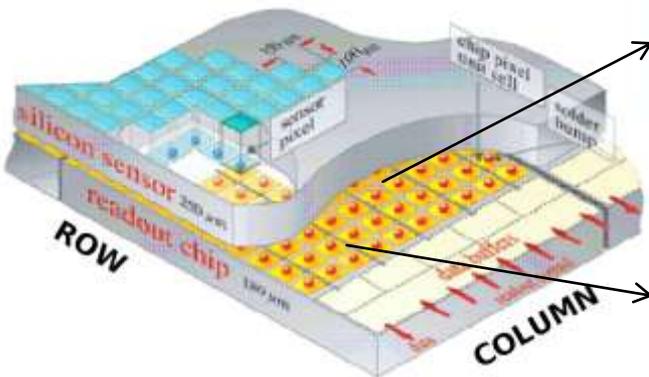
Pannels of the Forward Pixel Detector



Modules of the Barrel Pixel Detector

- Forward Pixel Detector (**FPix**) has two disks on each side at 34.5 cm and 46.5 cm
- FPix has 672 modules
- Barrel Pixel Detector (**BPix**) has 3 layers of radii 4.3 cm, 7.2 cm and 11.0 cm
- BPix has 768 modules
- Total of **~15,840 Readout Chips**

The Pixel Sensor and the Read Out Chip



- ReadOut Chip (ROC) bump bonded sensor pixels.

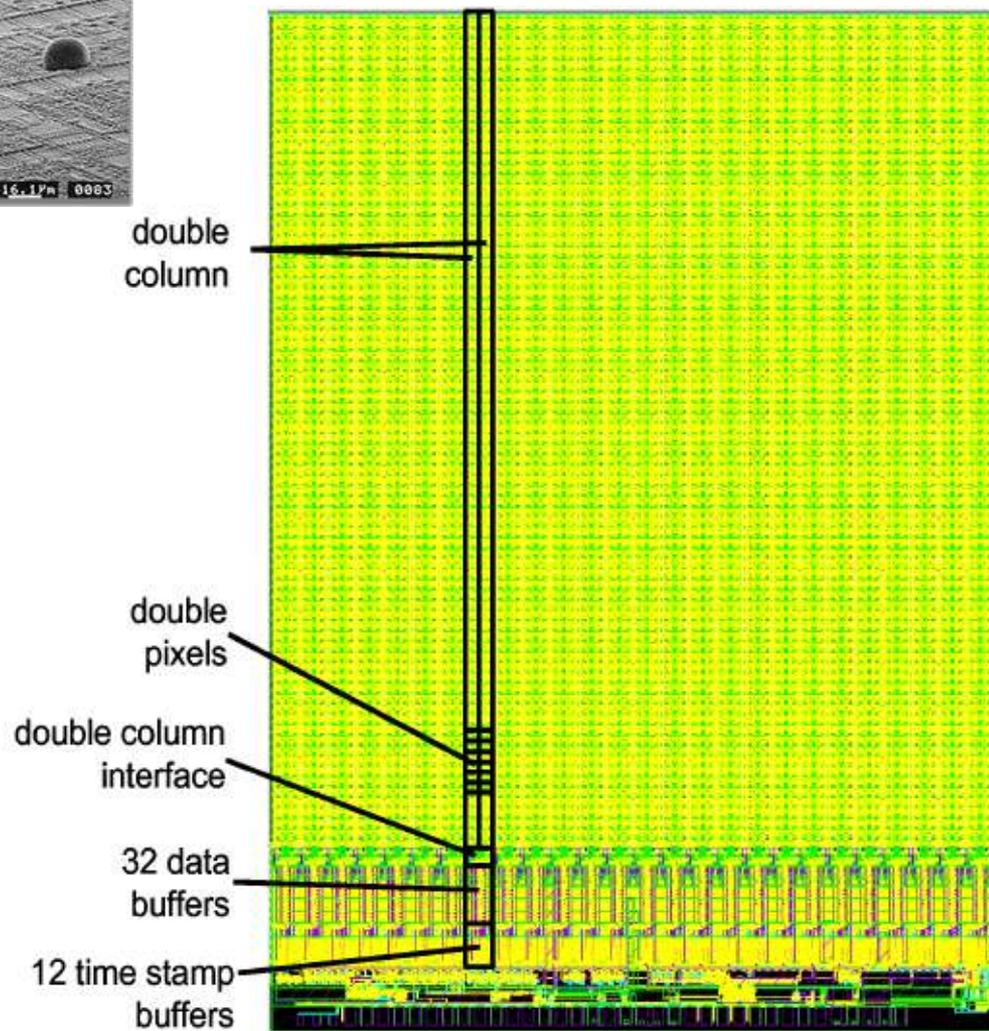
- $52 \times 80 = 4160$ pixels per ROC

- 15,840 ROCs

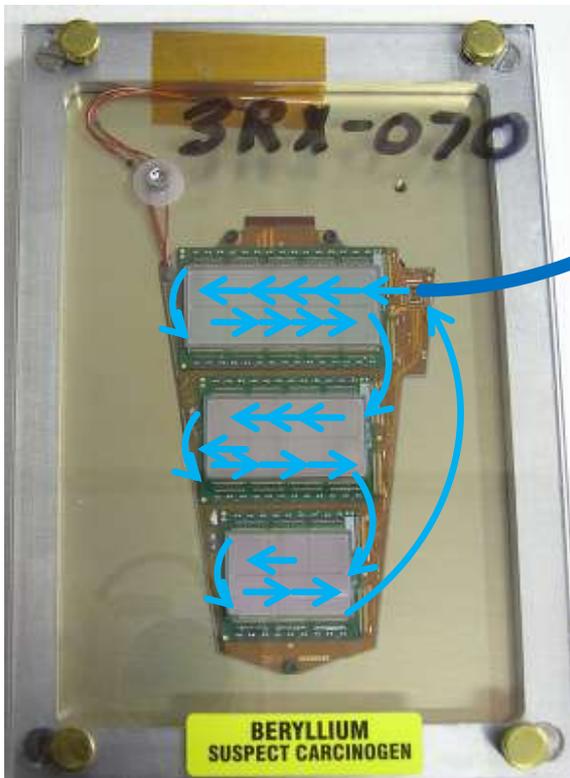
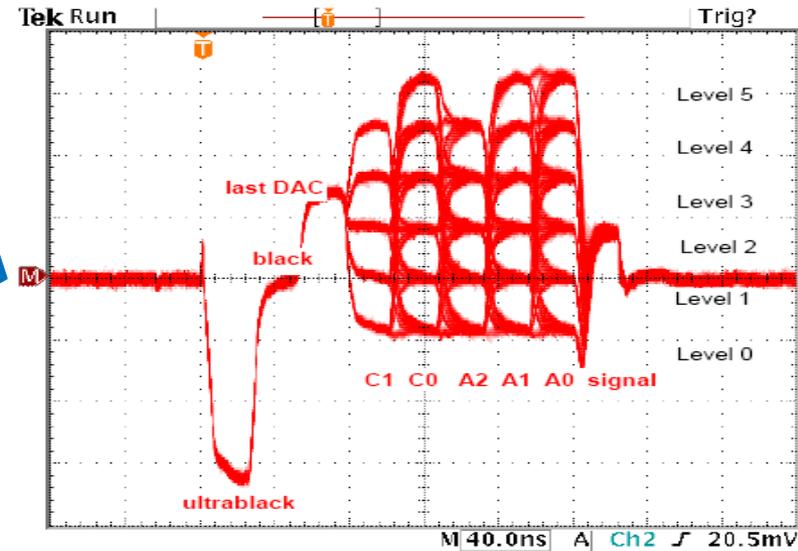
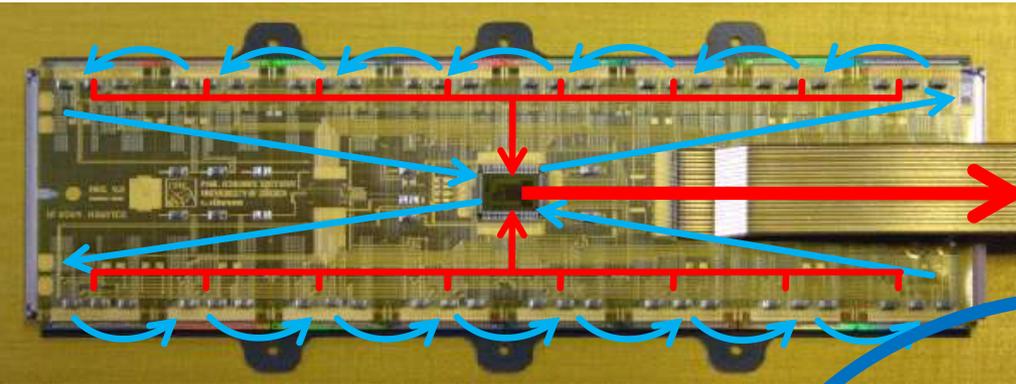
- 66 million pixels

- Automatic zero-suppression

- Each pixel has a programmable threshold (adjusting this is called *trimming*)

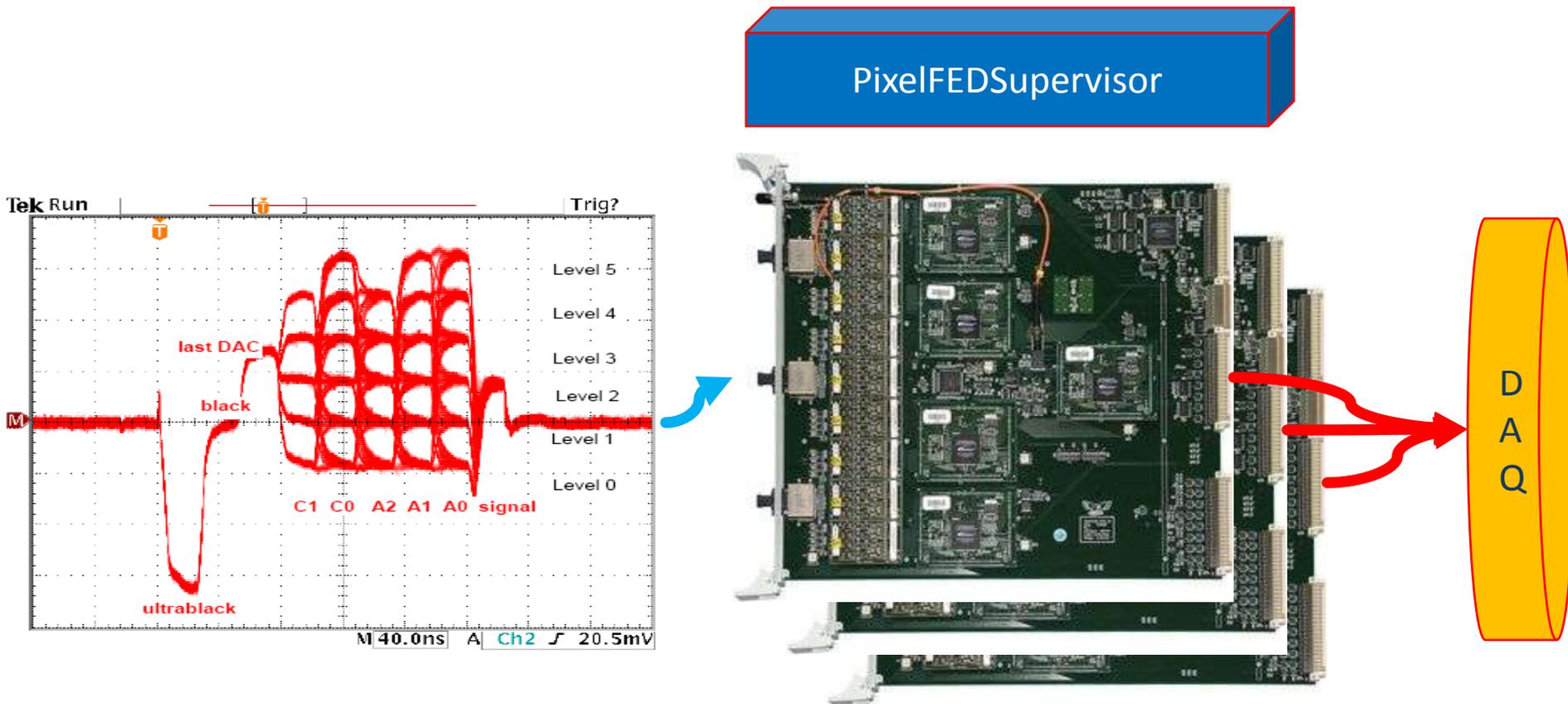


Forward and Barrel Pixel Analog Readout



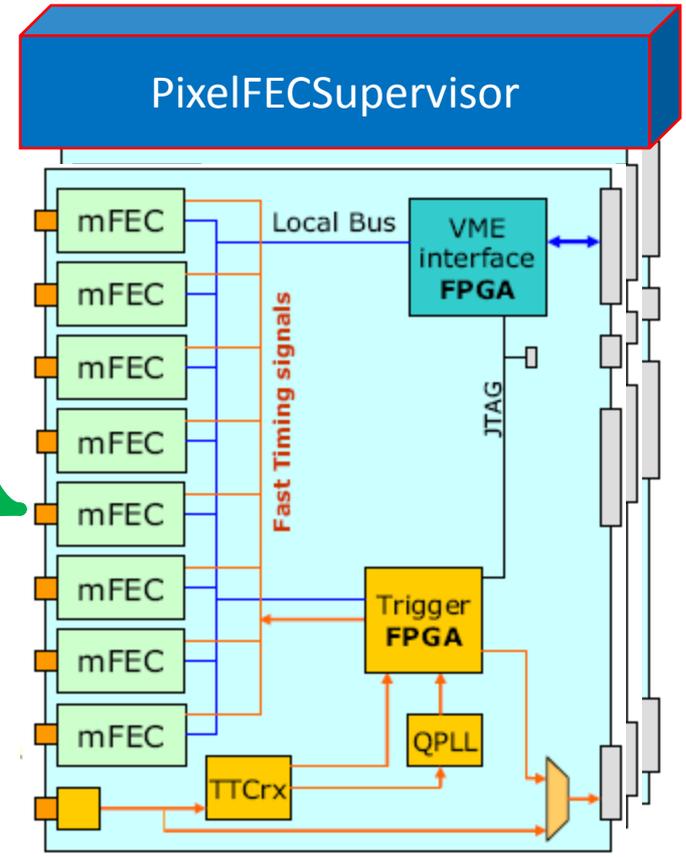
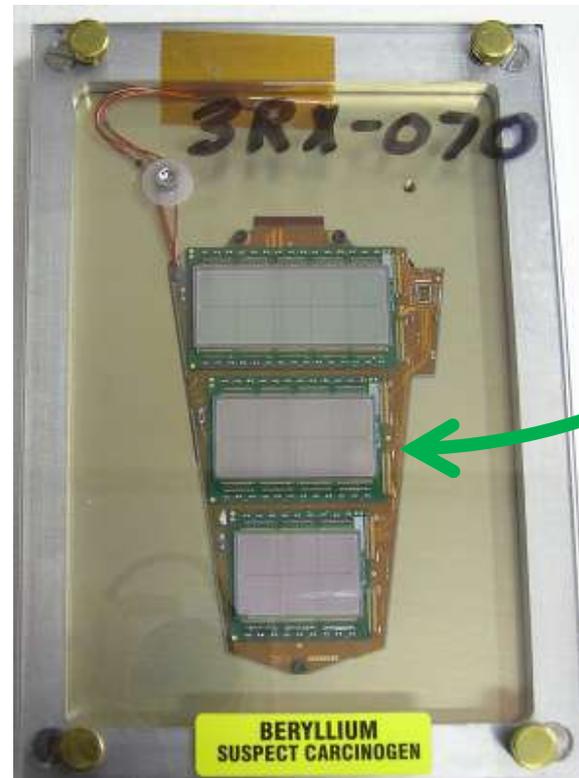
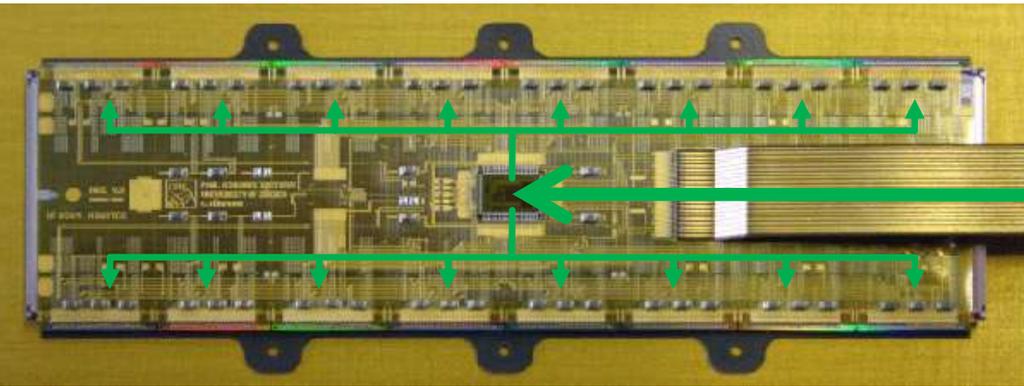
- On receiving a L1 trigger, the Token Bit Manager (TBM) initiates a Chinese-whisper of “token bits” that instruct each ROC to send its hit data to the TBM
- The signal from the TBM is electrical and analog. It encodes the ROC #, row and column and charge deposit of each pixel hit
- The electrical signal from the TBM is converted to optical by the Analog-Optical Hybrid (AOH)

Digitization of Analog Readout with the Front End Driver



- Pixel Front End Driver (FED) digitizes analog signals given the level thresholds for decoding.
- One crate of FED boards is controlled by one PixelFEDSupervisor application. 40 FEDs in Pixels.
- FEDs send digitized data down S-Link cables to the Data Acquisition System (DAQ).
- FED data may also be read out via VME by the PixelFEDSupervisor.

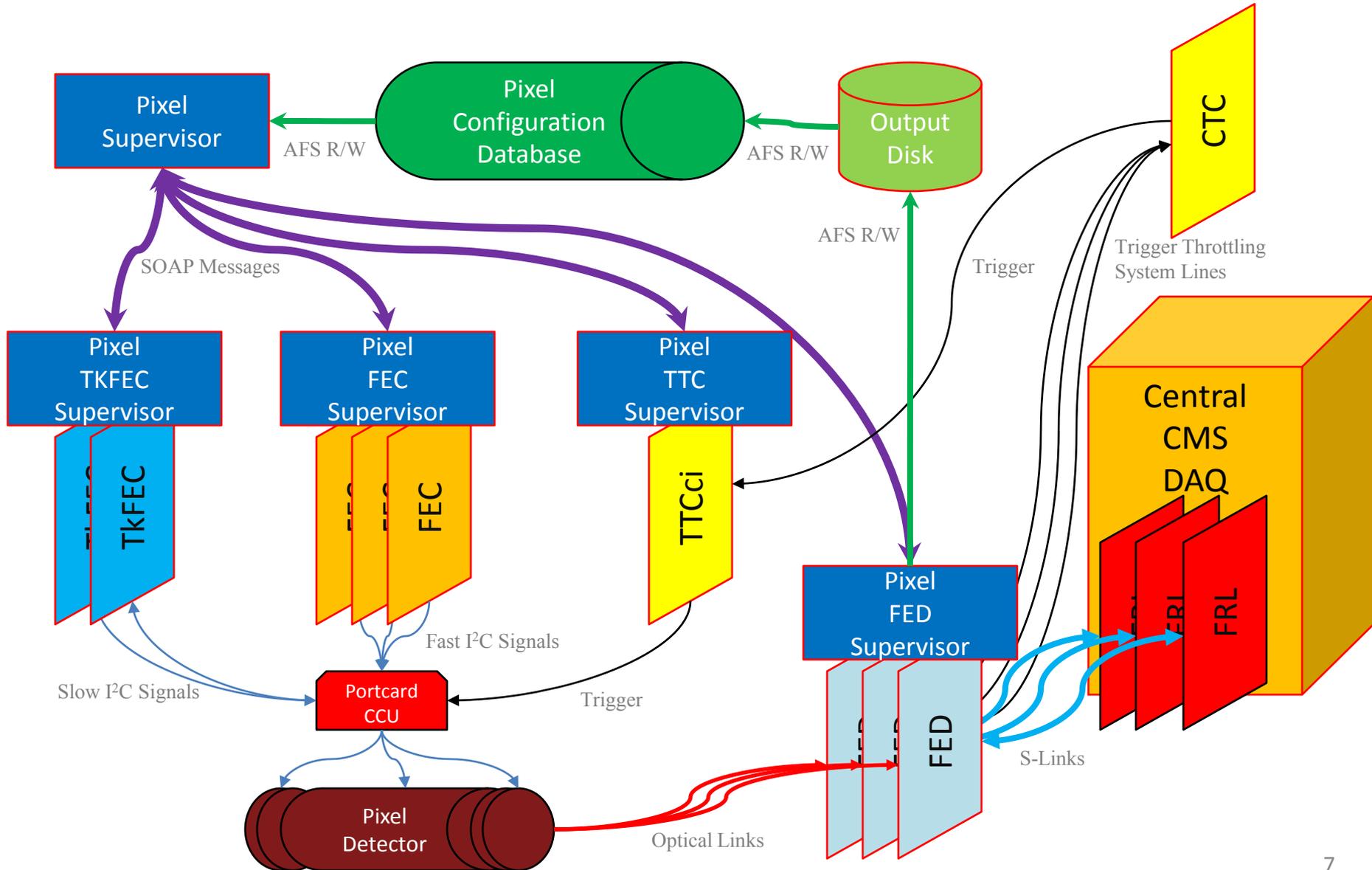
Barrel and Forward Pixel Programming Chain



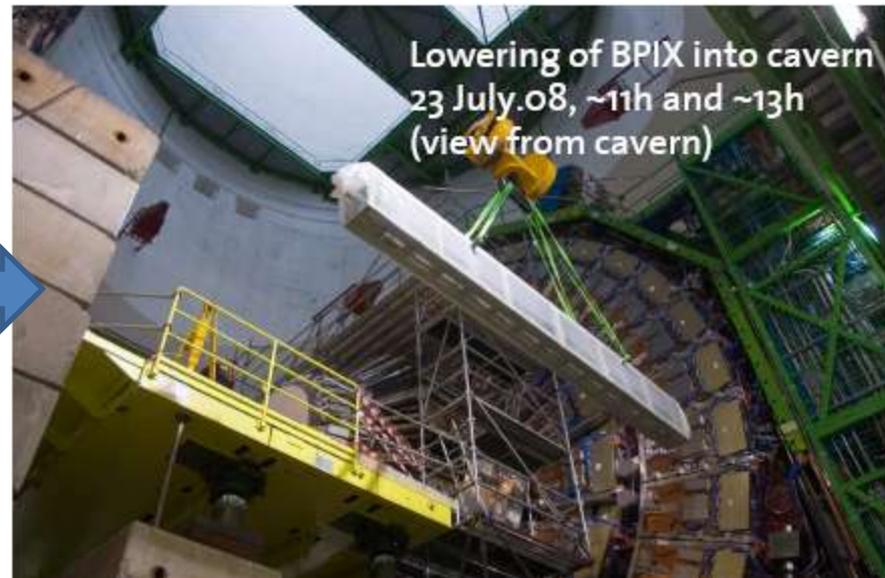
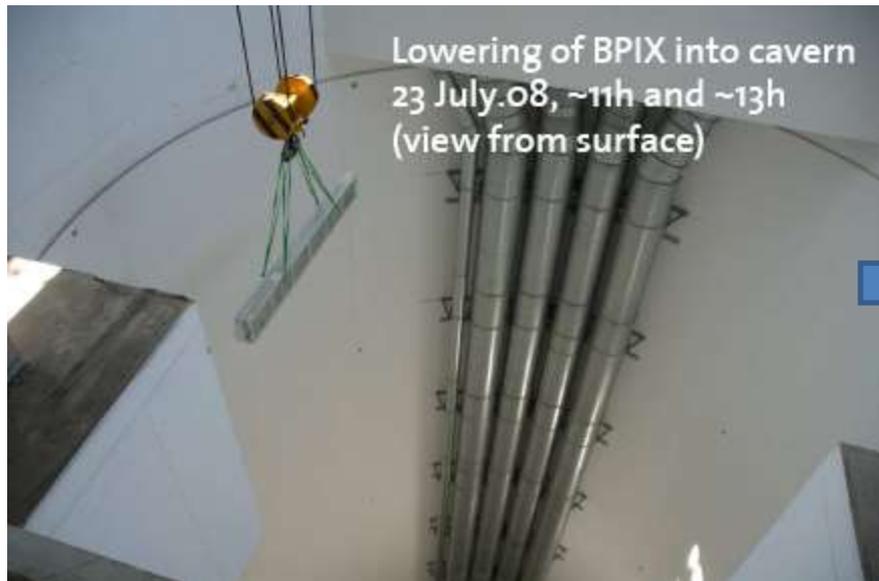
- Control signals consist of
 1. Clock & L1 Trigger
 2. I²C Commands for programming

•Using I²C commands we can program various DACs on each ROC, set trim bits on each pixel and inject charges for calibration purposes.

Pixel Data Acquisition Software



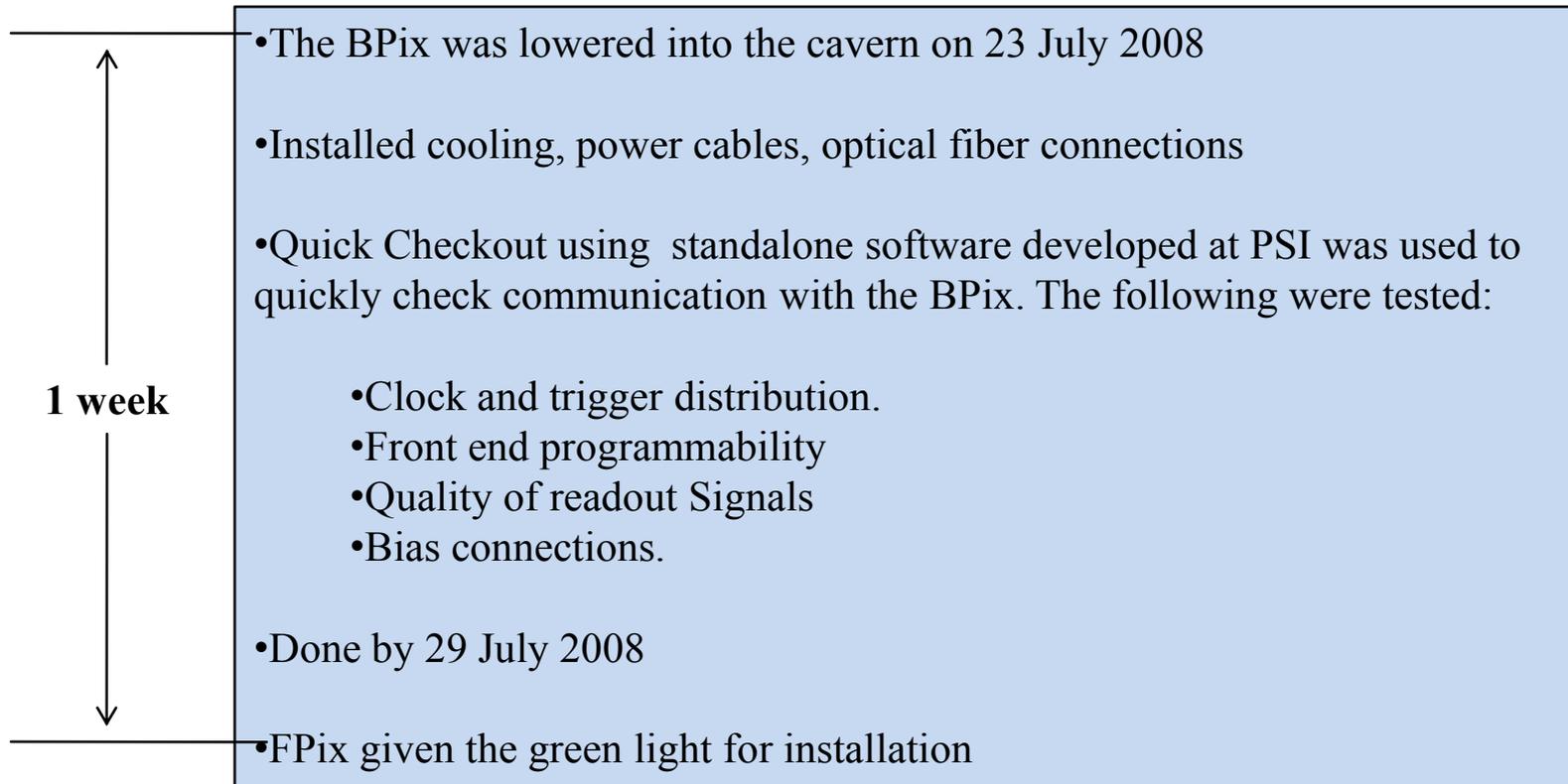
Lowering the Barrel Pixels into the Cavern



Inserting the Barrel Pixels into CMS



Quick Checkout of the Barrel Pixels



Inserting the Forward Pixels into CMS



The FPix being slid in with the BPix in place.



Synchronous insertion of the inner and outer half-cylinders.

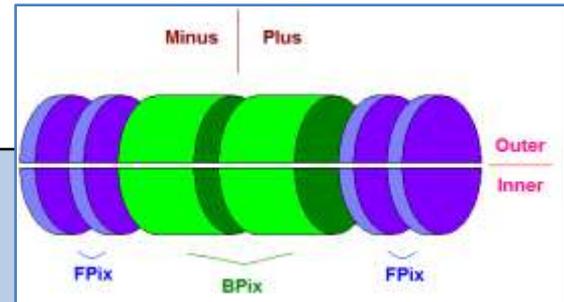
Cabling and cooling after insertion



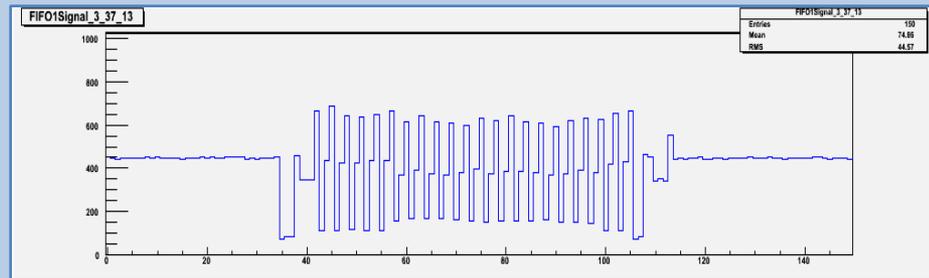
Viola, Monsieur!



Quick Checkout of the Forward Pixels

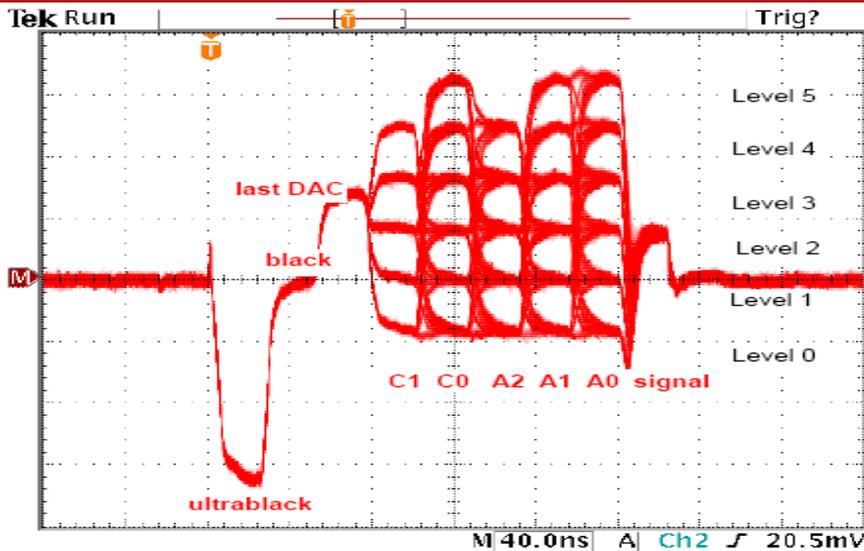


- 1 week
- FPix services connected by 31st July 2008
 - Quick Checkout using Pixel Data Acquisition Software one Half Cylinder at a time:
 - Ensure correct mapping of the data fibers
 - Appropriate change of drawn current on configuring the Readout Chips
 - Stable baseline of the TBM analog signal (*FEDBaselineCalibration*)



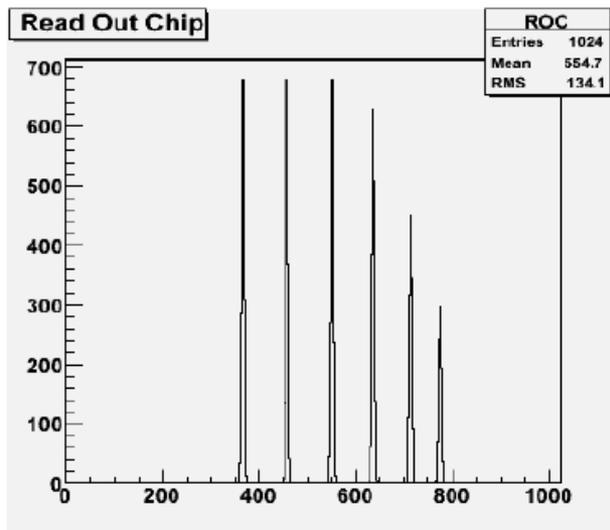
- Some panels required cleaning of the optical fiber. Baselines stabilized.
- CMS Pixel Detector closed on 7th August 2008

Address Levels Calibration during Second Commissioning Phase



The analog signal from the TBM

Good separation: rms is ~ 2.5 ADC



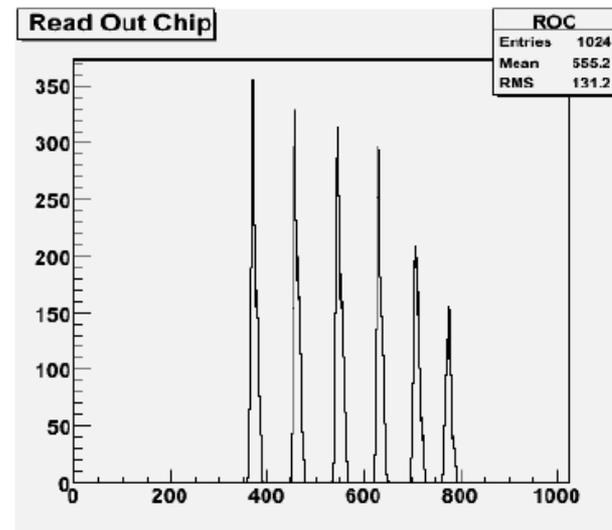
Address Levels Calibration

For the FED to decode the analog output of the TBM, it must know the address level thresholds.

Address level peaks may get smeared out when:

- The FED samples the signal at the wrong time
- The baseline is jittery due to unclean optical fibers

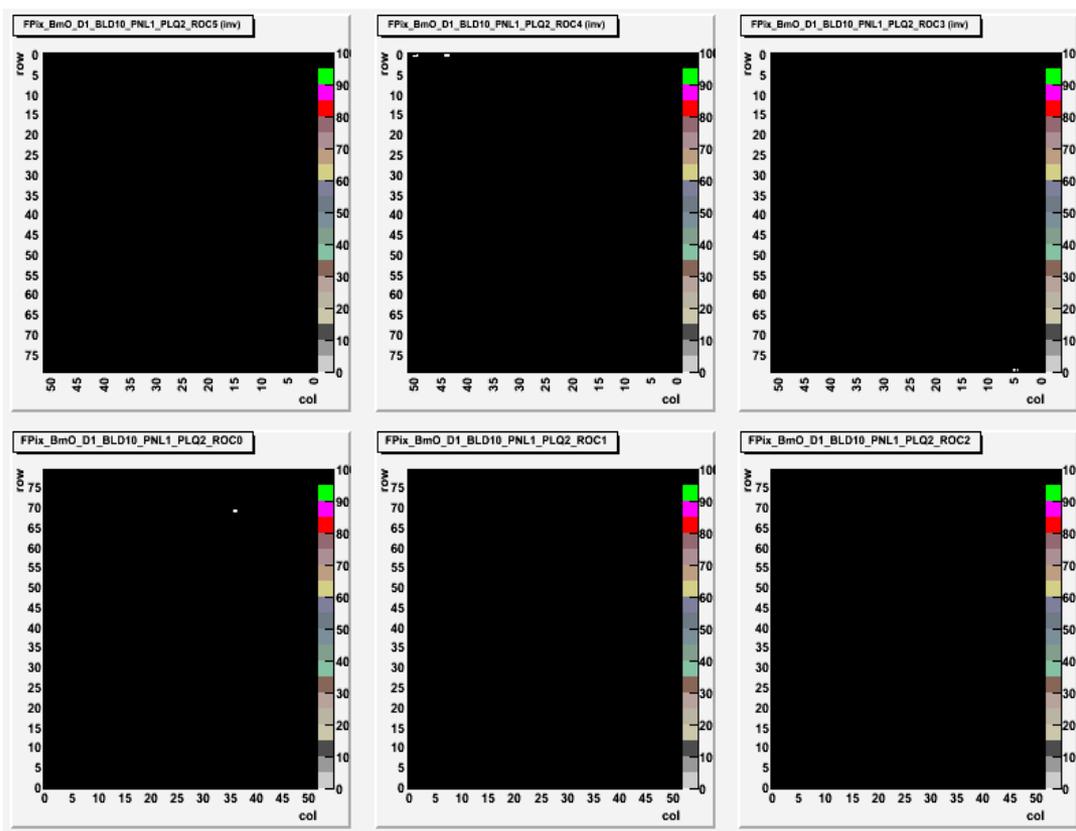
Poor separation: rms is >5 ADC



Pixel Alive Scan during Second Commissioning Phase

Pixel Alive

Inject charge repeatedly into each pixel and see how often they respond.
Build up an efficiency map and identify defective pixels.



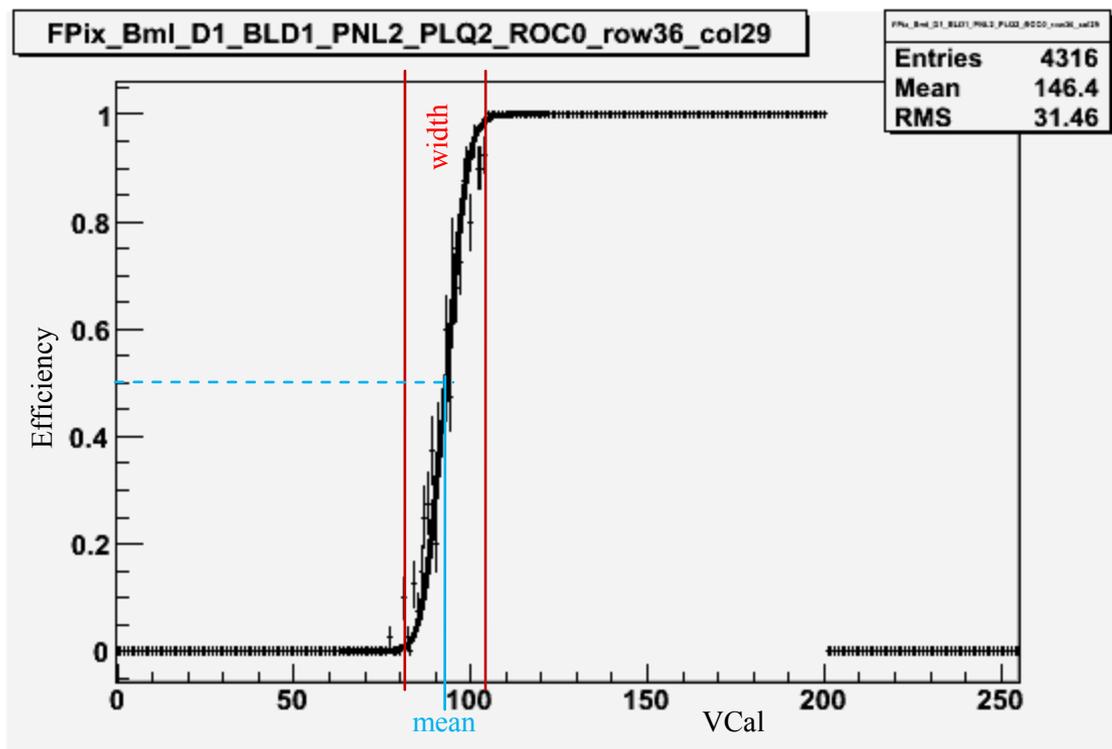
Dead Pixels

0.010% of BPix
0.015% of FPix

S-Curve Calibration during Second Commissioning Phase

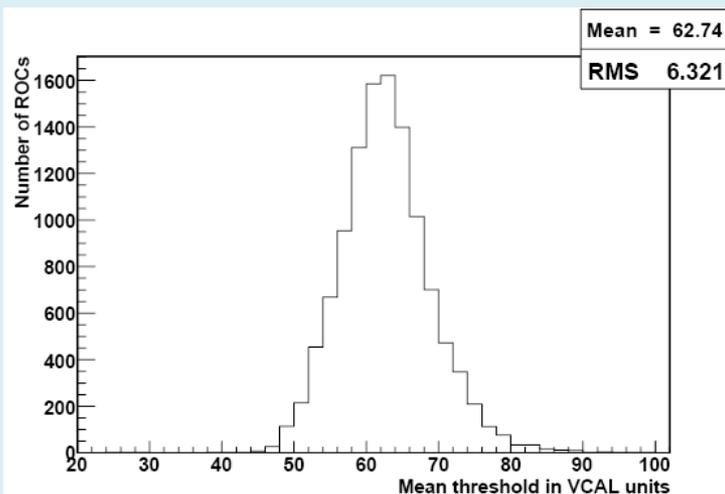
S-Curve Calibration

The charge injected into each pixel for calibration, governed by V_{Cal} , is varied. The efficiency of pixel response against the change in V_{Cal} gives us an S-Curve



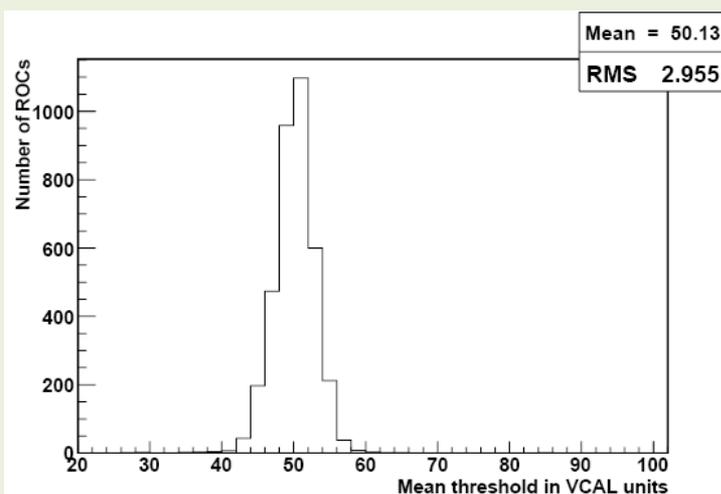
- The V_{Cal} corresponding to 50% efficiency is the **threshold** of response.
- The width of the turn-on region is a measure of the pixel's **noise**.
- One unit of V_{Cal} is roughly **65 electrons**.

Pixel Thresholds from S-Curves during Second Commissioning Phase



Threshold distribution for *un-trimmed* Barrel Pixels.

Mean corresponds to $\sim 3690 e^-$

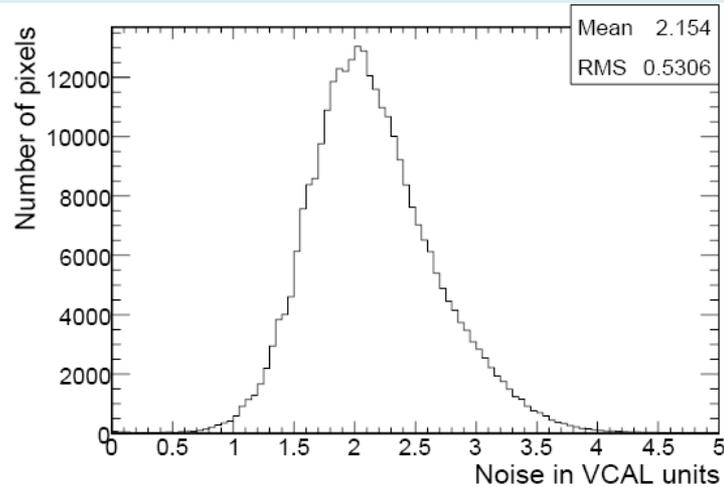


Threshold distribution for *trimmed* Forward Pixels.

Mean corresponds to $2870 e^-$

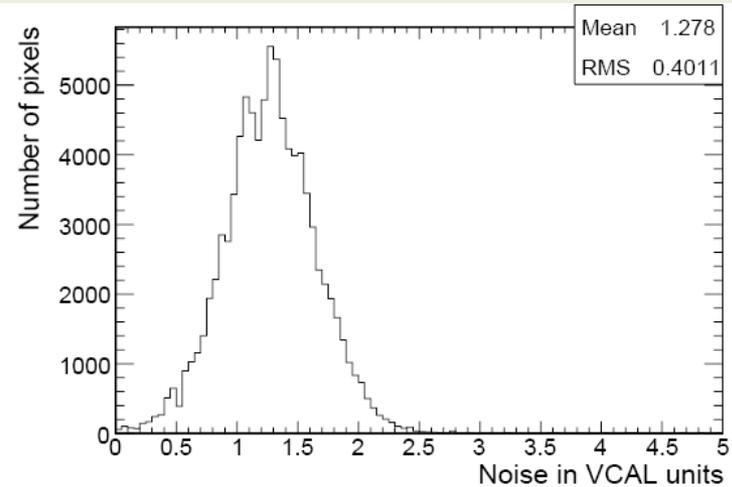
Threshold well below the minimum ionizing particle $\sim 22,000 e^-$

Pixel Noise from S-Curves during Second Commissioning Phase



Noise distribution for the Barrel Pixels.

Mean corresponds to **141 e⁻**

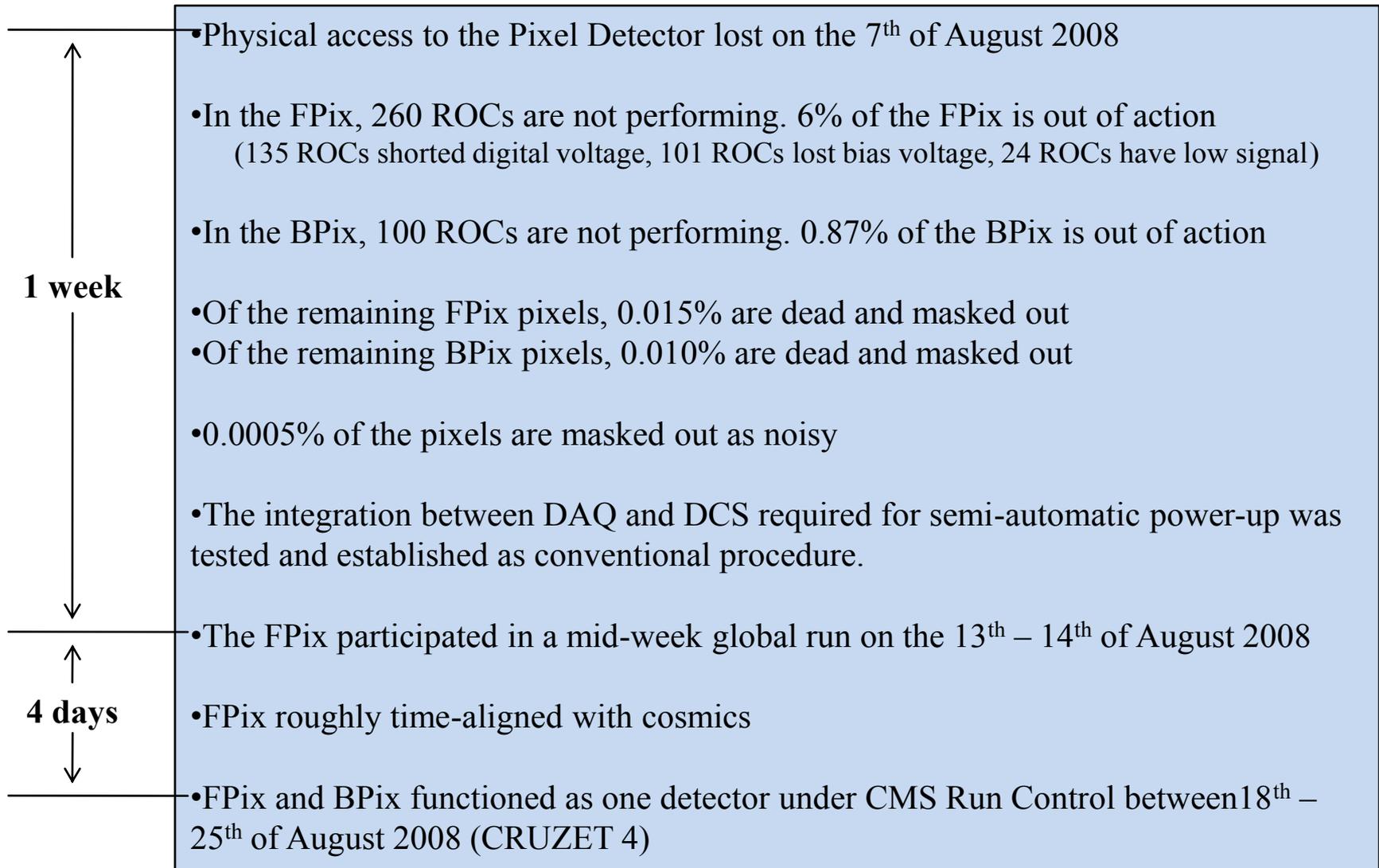


Noise distribution for the Forward Pixels.

Mean corresponds to **85 e⁻**

Level of noise does not significantly degrade response of the detector

Results of the Second Phase of Commissioning



Time Alignment in the Third Phase of Commissioning & Global Run

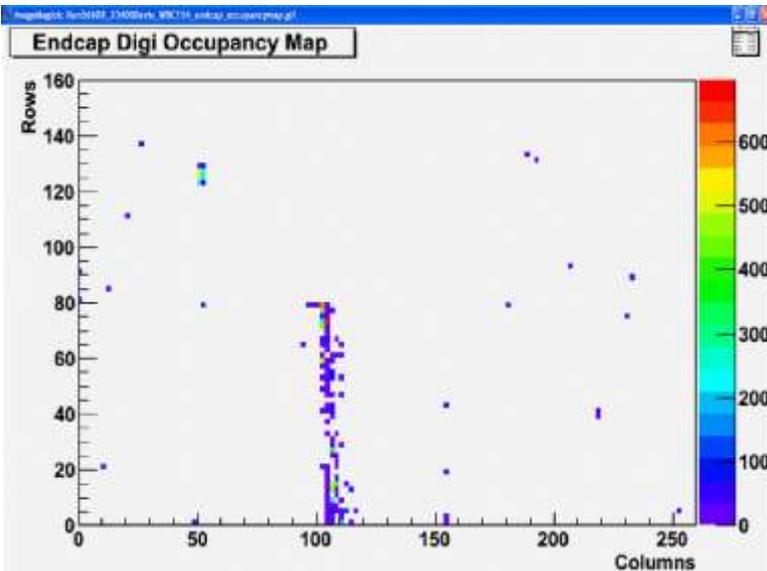
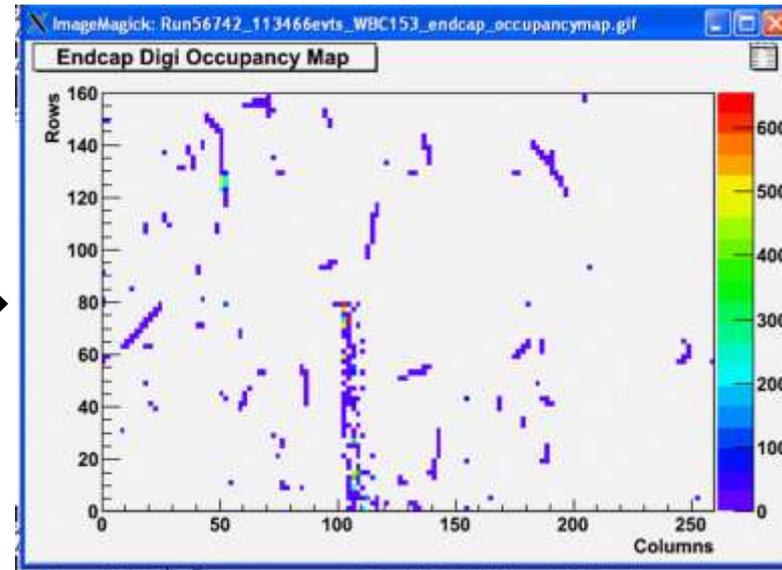
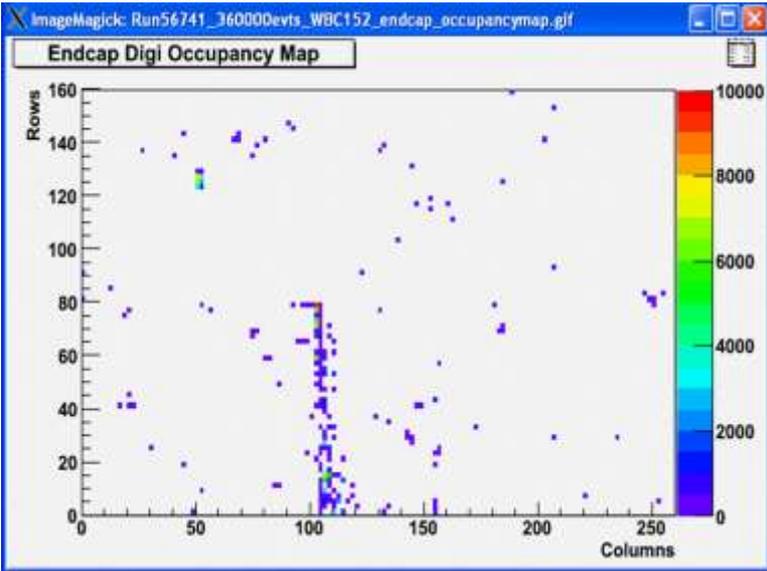
The Final Stage of Time Alignment in the FPix with Cosmics

← Misaligned (No Tracks)

Aligned → (Tracks!)

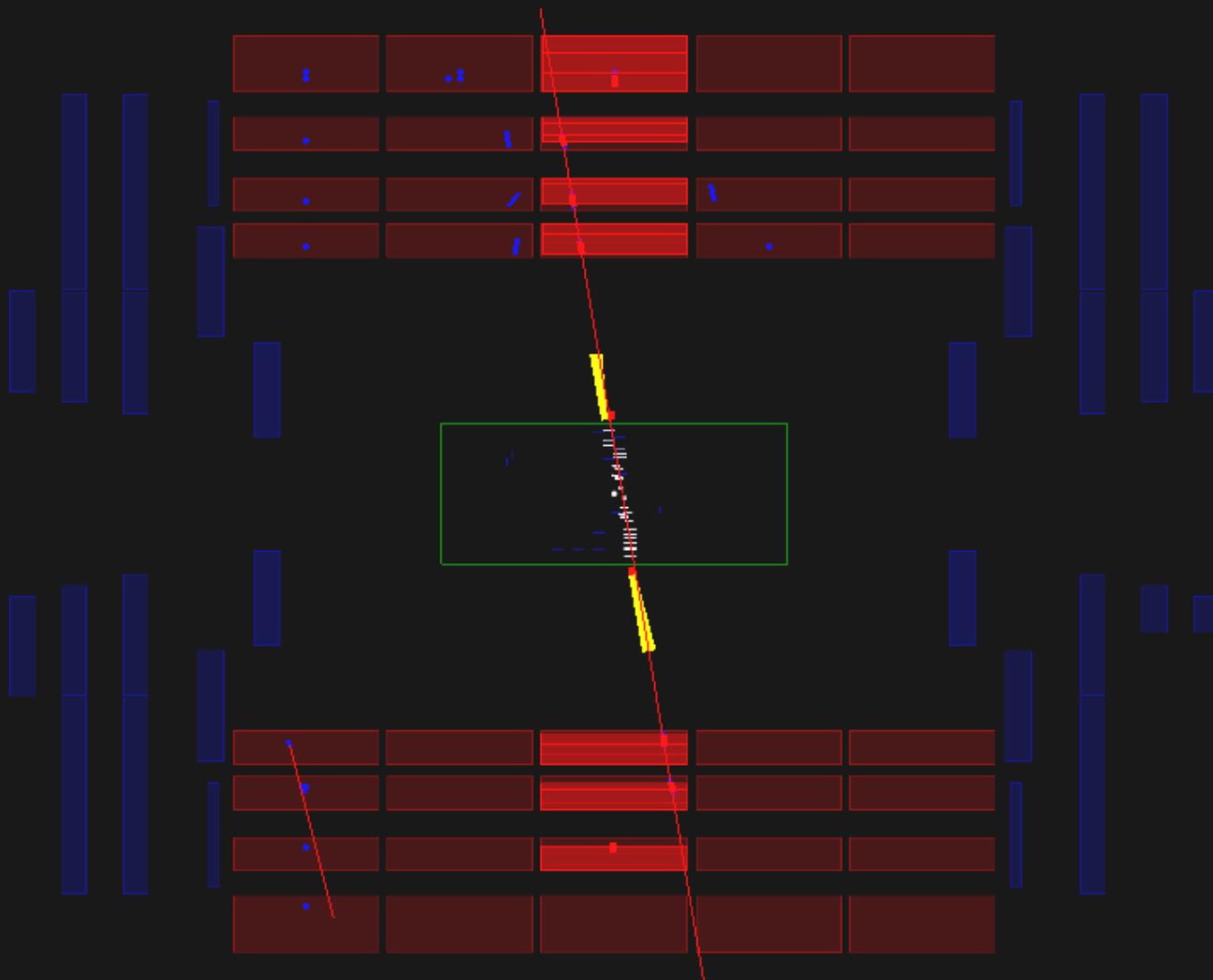
← Misaligned (No Tracks)

Hot pixels at the edge of a module

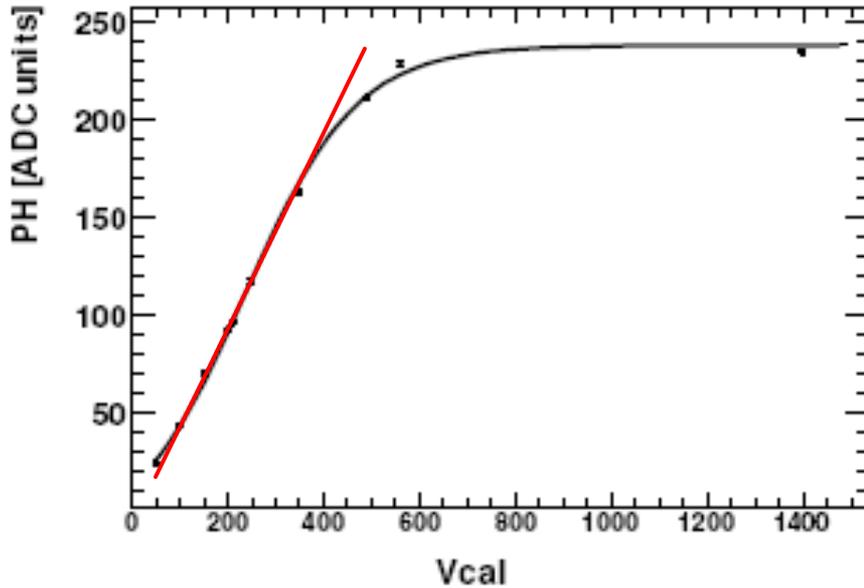


Cosmics in CRUZET 4

200



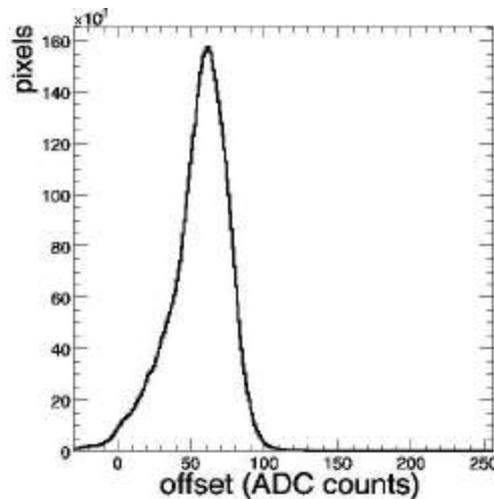
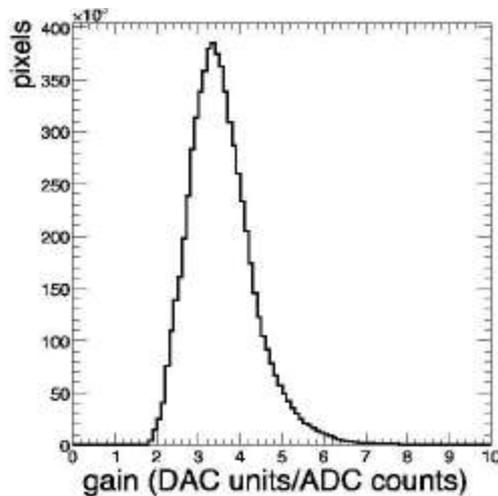
Gain Calibration



Gain Calibration

The charge injected into each pixel for calibration, governed by V_{Cal} , is varied.

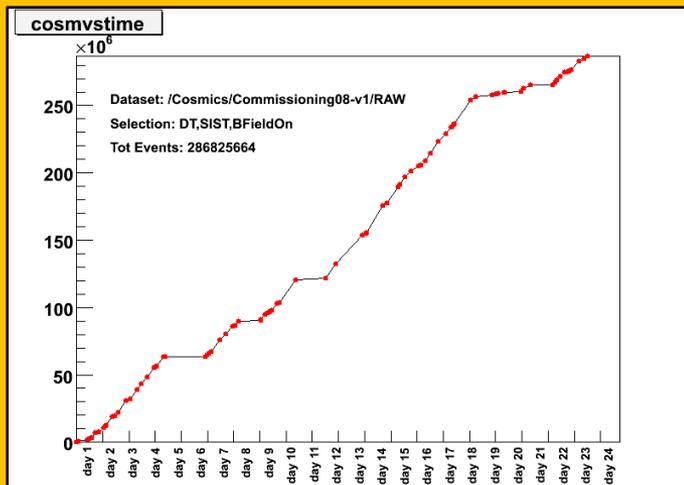
The pulse height in ADC counts plotted against the V_{Cal} gives us the Gain Curve



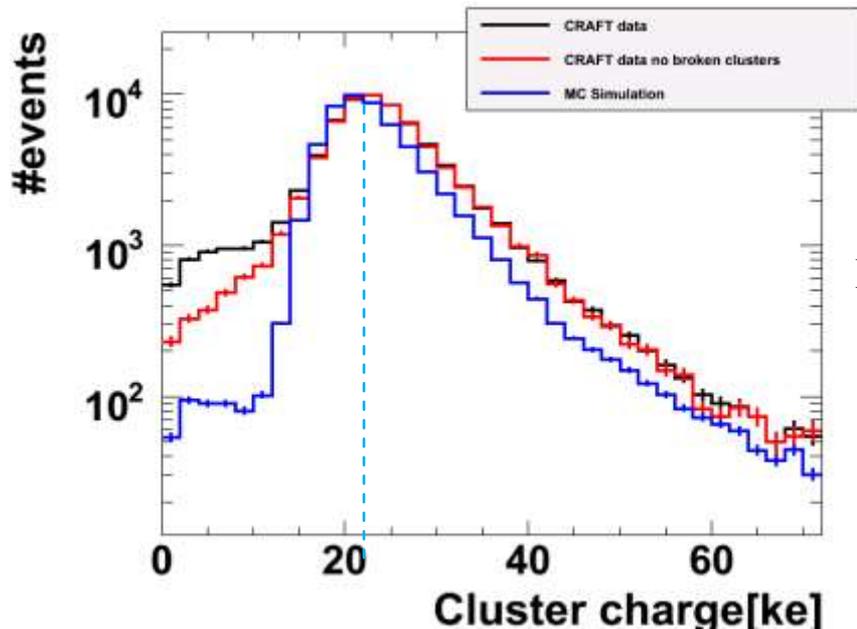
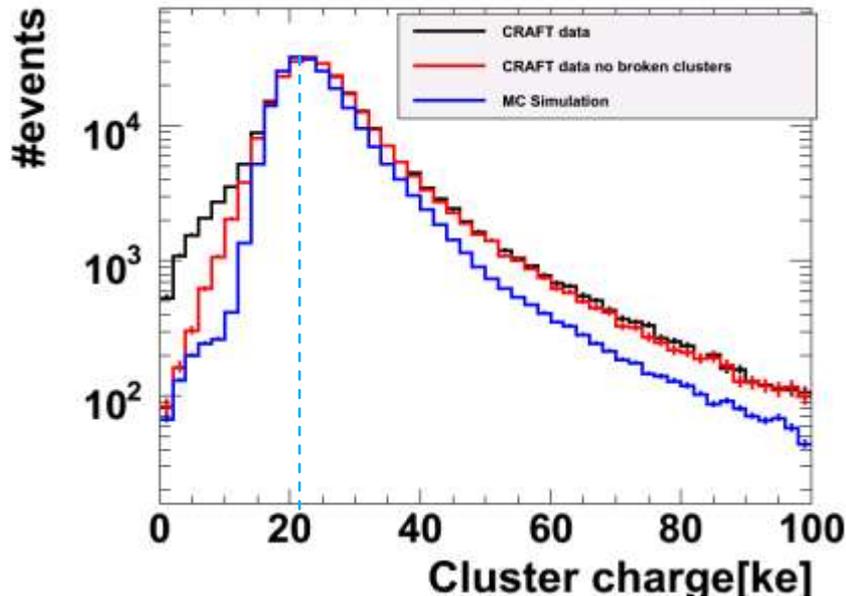
- **Linear fit** between the Pulse Height read out by the FED and the charge in V_{Cal} units or electrons it represents.
- Mean of slope = 3.6 (DAC/ADC)
- Offset = 55 ADC
- Used for **calculating charge deposited** in clusters (position average)

Charge Collection

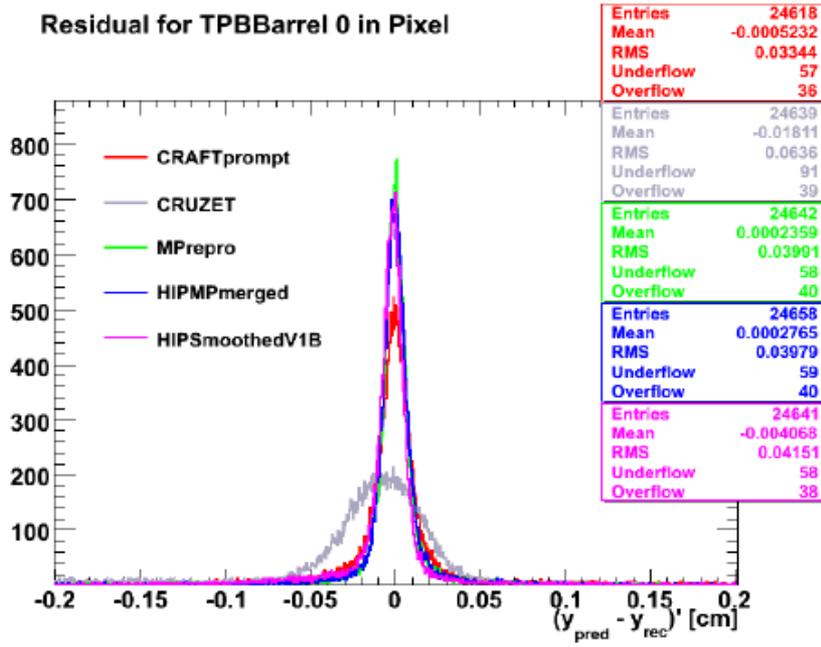
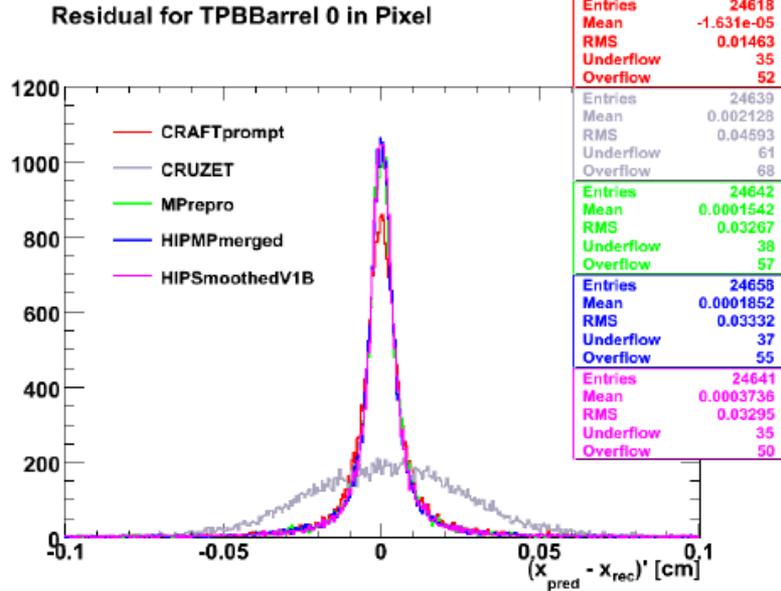
- CRAFT (Cosmic Run at Four Tesla) at 3.8 T took about 370 million events.



- 80,000 tracks recorded through the Pixel Detector
- Cluster charge normalized to $285 \mu\text{m}$ gives a Landau distribution with peak at $\sim 22,000 e^-$



Track Quality after Rough Alignment



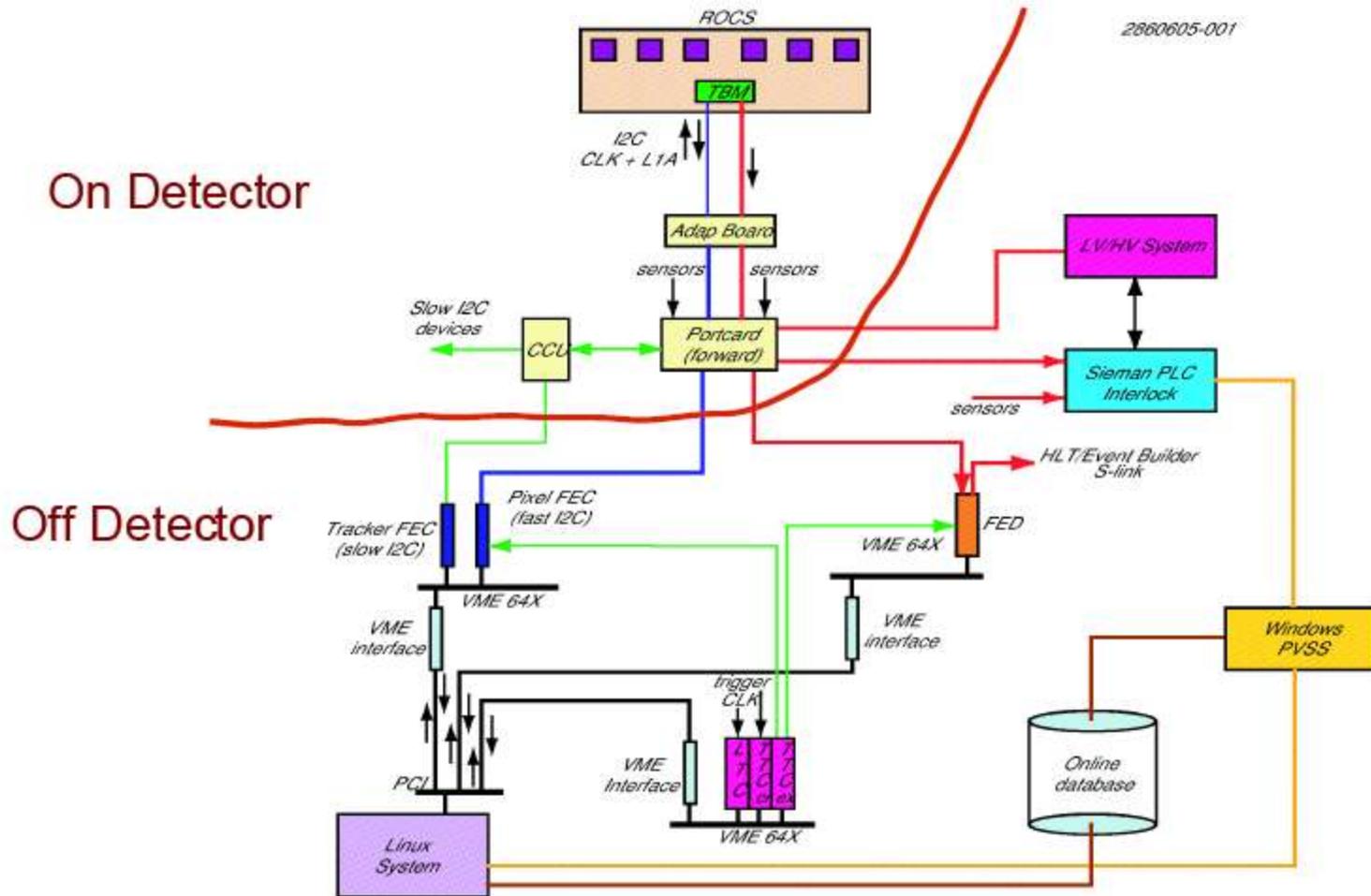
- Barrel Pixels aligned at module level
- **CRUZET** is the nominal geometry
- **CRAFT-HIP** and **CRAFT-MP** are two alignment algorithms applied to the CRAFT data
- Significant narrowing of track residuals

Conclusions

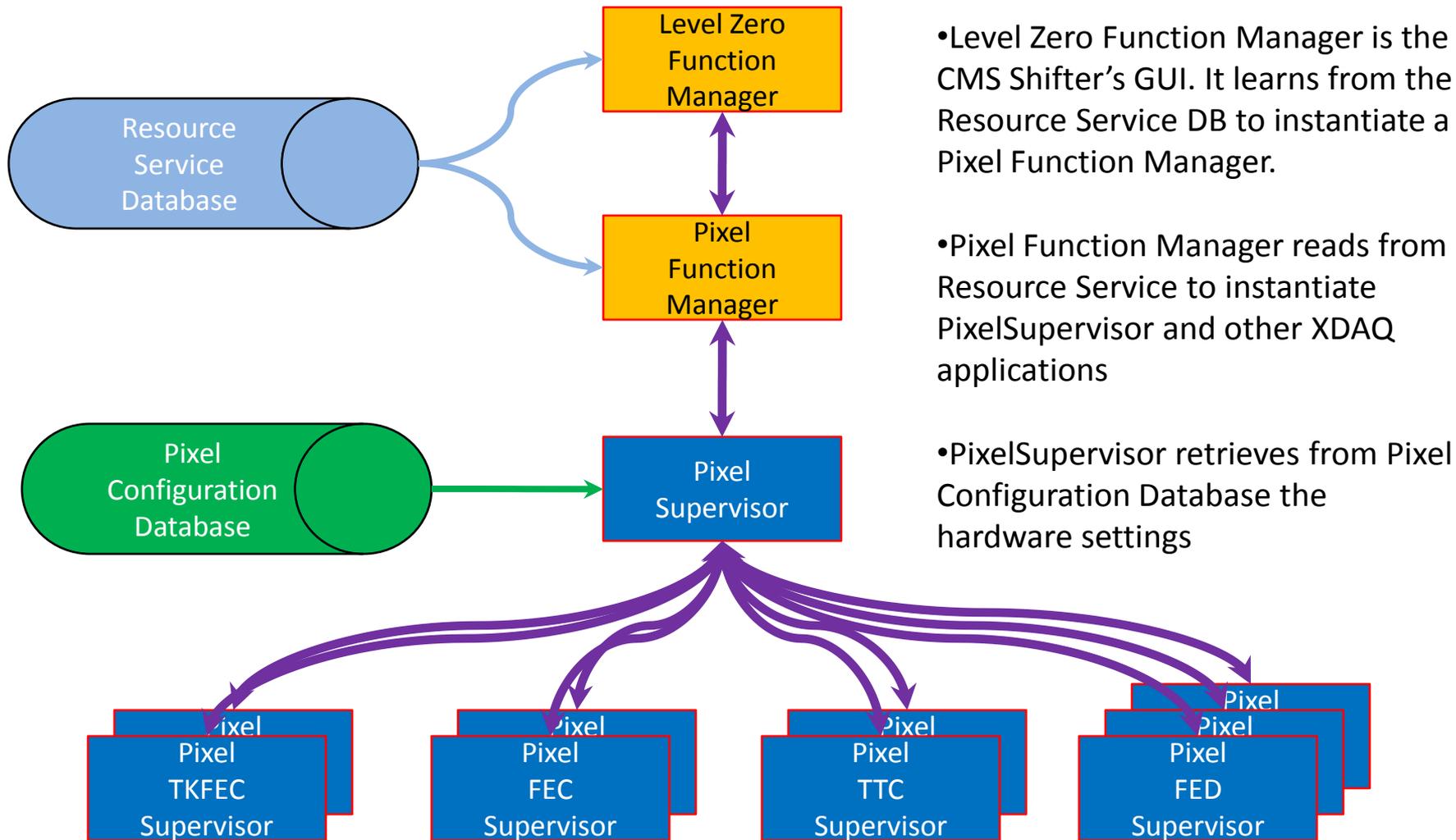
- The CMS Pixel Detector was installed successfully within a very tight schedule (days!)
- Commissioned in two weeks
- Participated in Cosmic Run at Zero Tesla (CRUZET 4) as one detector.
- Participated in Cosmic Run at Four Tesla (CRAFT 3.8 T) as one detector. Data collected is being used for performance studies and alignment.
- 6% of the Forward Pixel Detector is damaged. It is being taken out and repaired over the 2008-2009 winter shutdown.
- Should be optimally ready for data taking in Spring 2009

Backup Slides

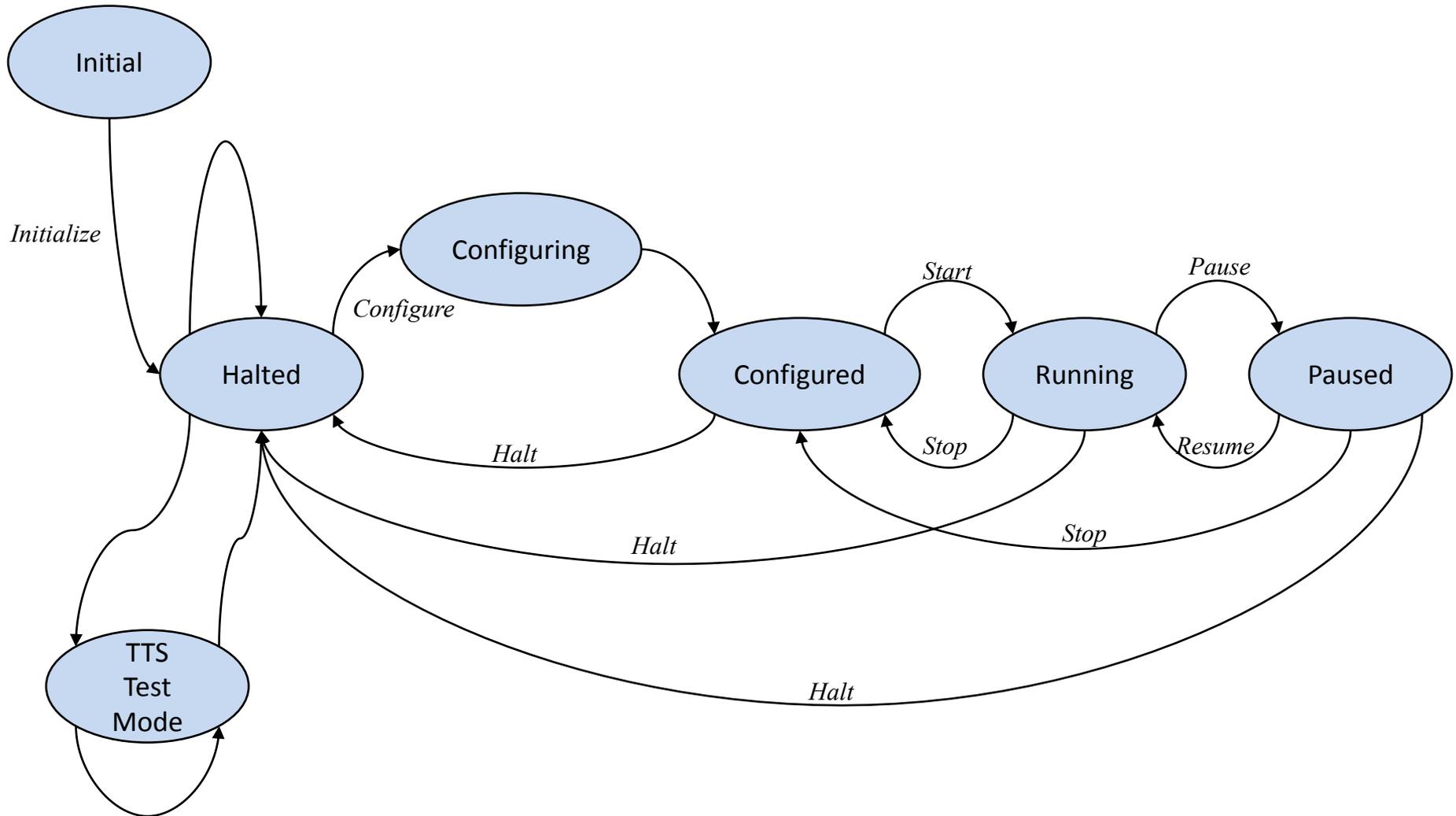
Pixel Control and Readout



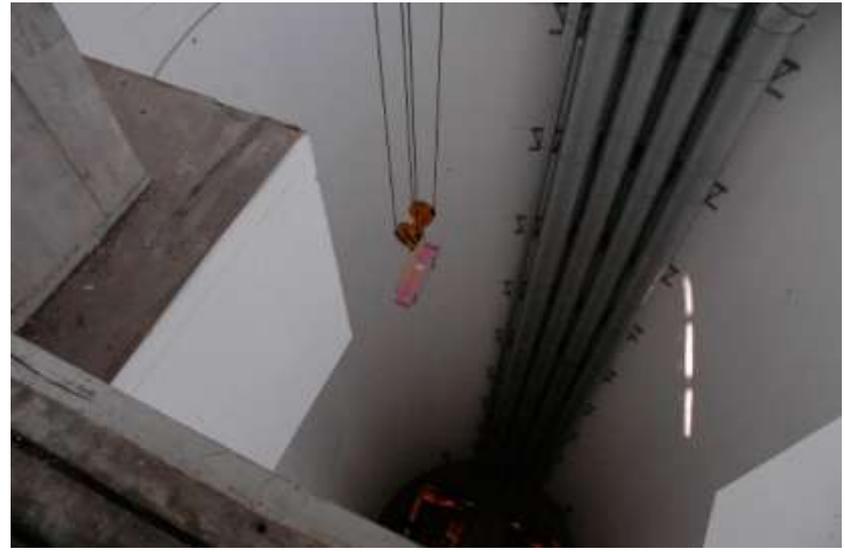
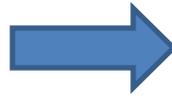
Pixel Online Software within the Run Control Framework



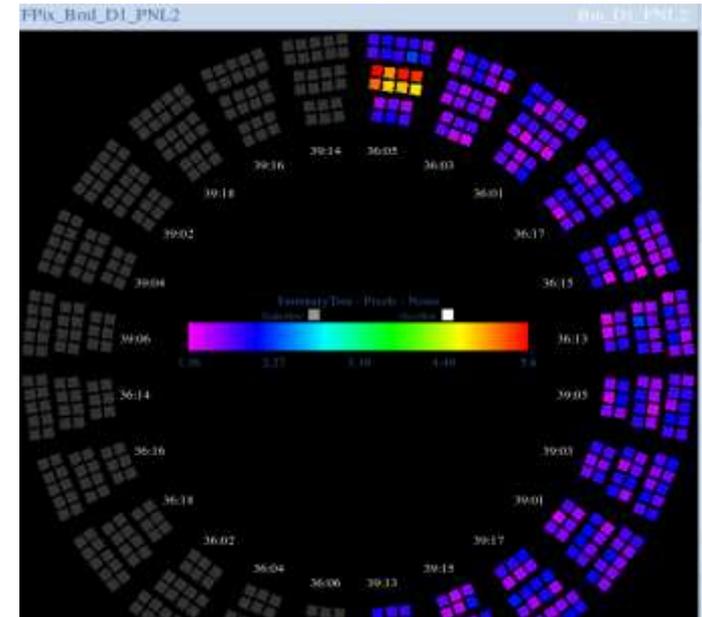
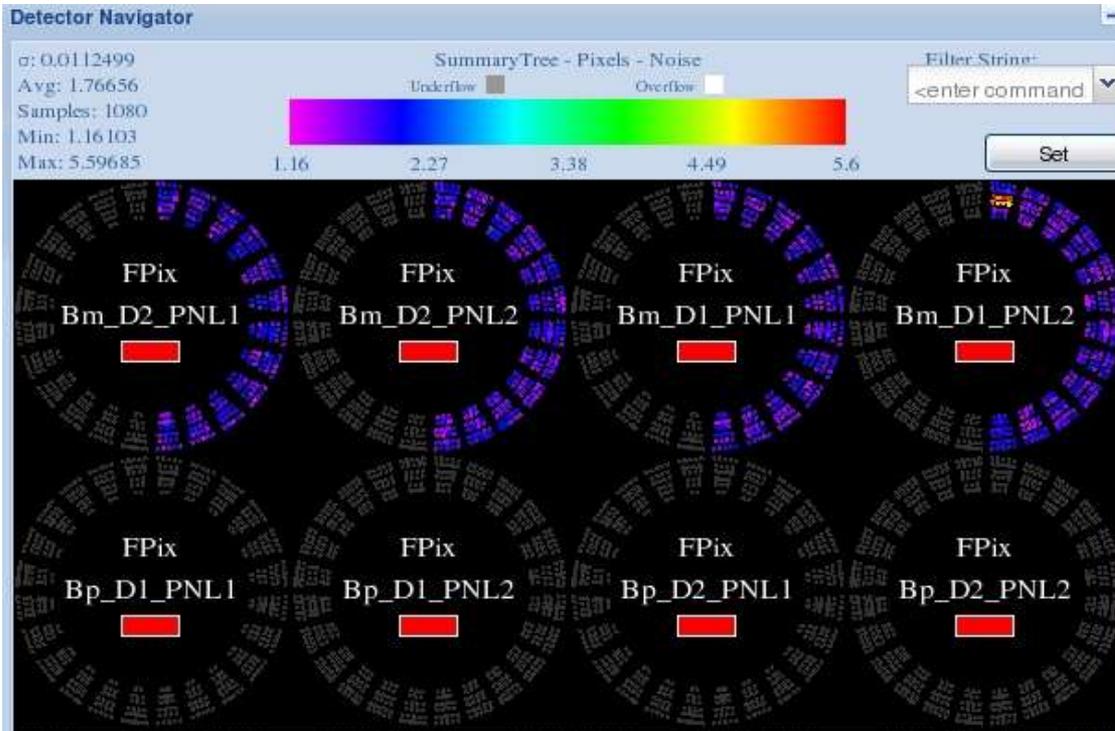
Finite State Machine Structure of PixelSupervisor



Lowering the Forward Pixels into the Cavern



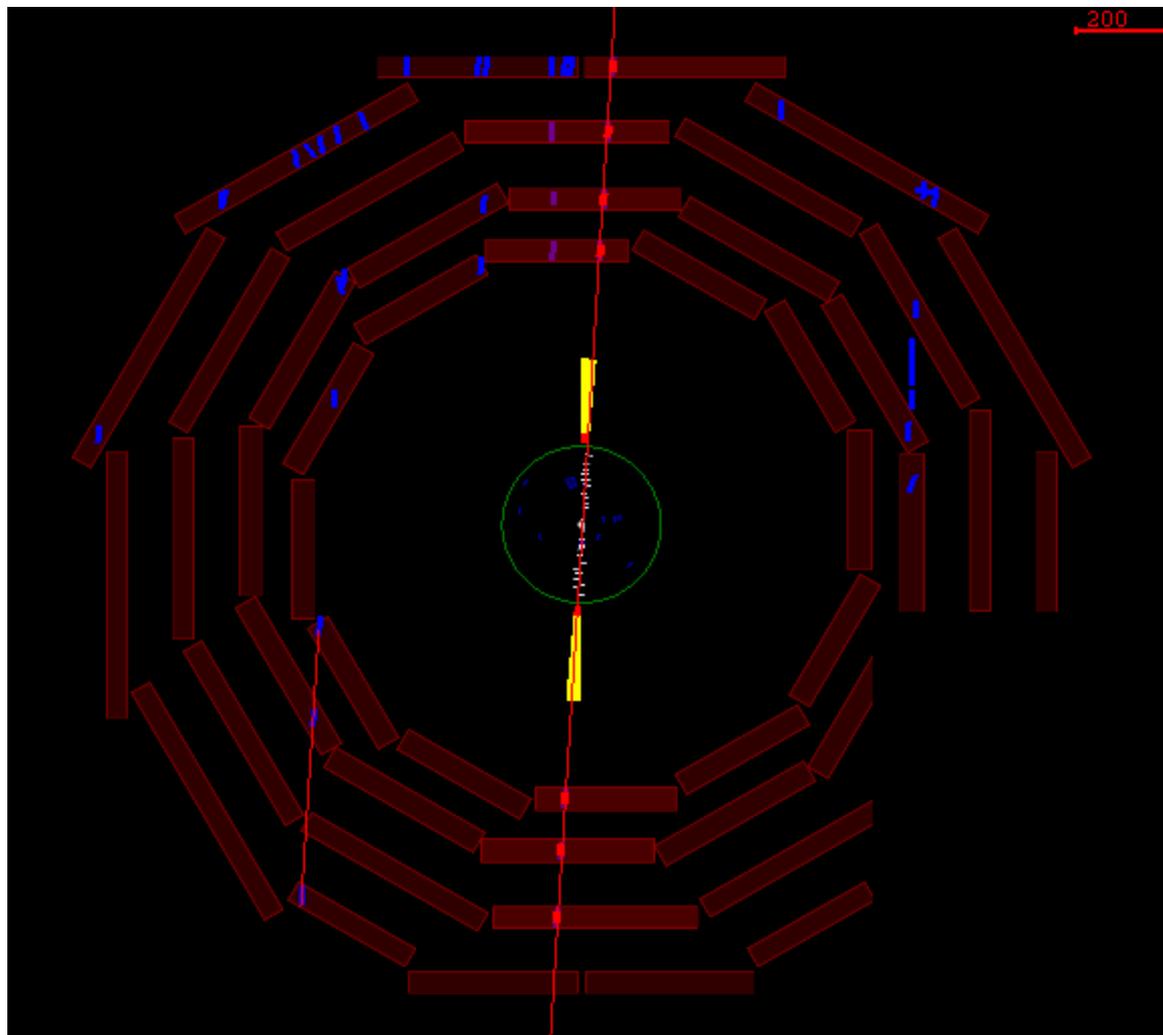
Commissioning Phase II – S-Curve Calibration



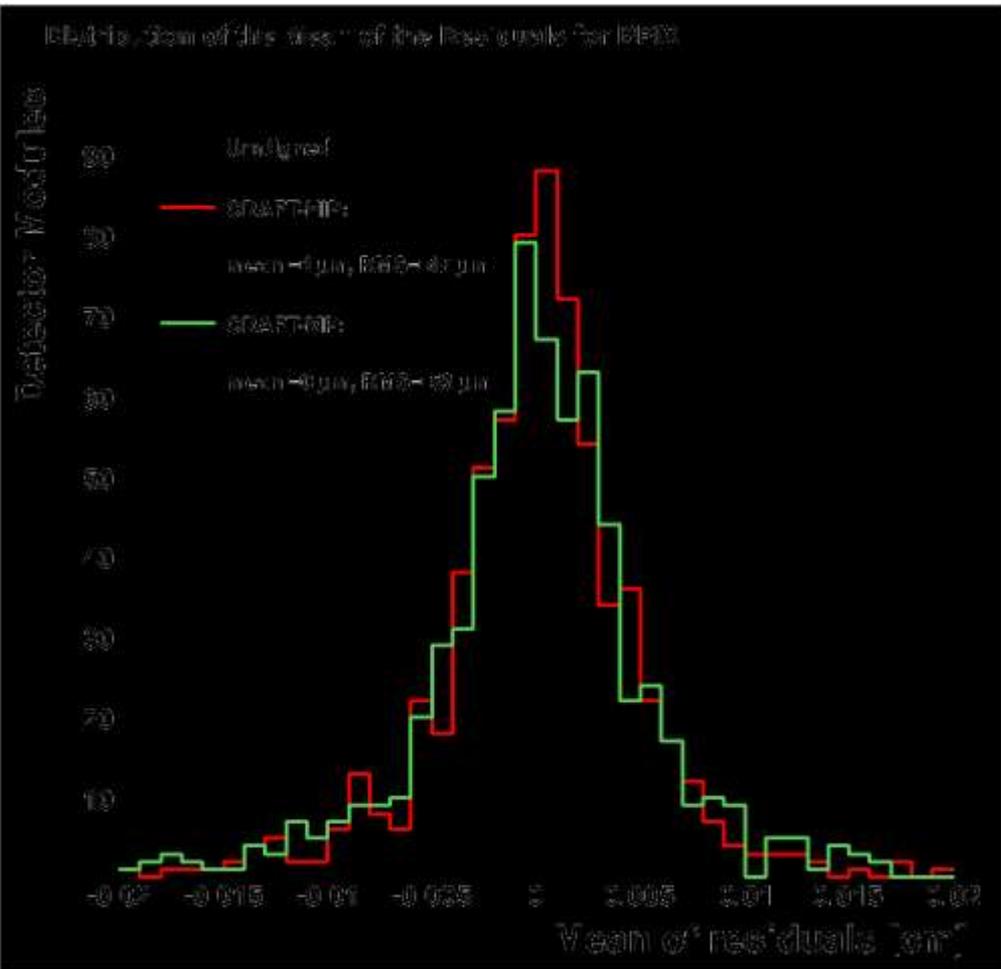
An S-Curve Showing the Broken High Voltage Wirebond

- *BmI_D1_PNL2* had been noted through inspection to have a broken high-voltage wirebond

Cosmics in CRUZET 4

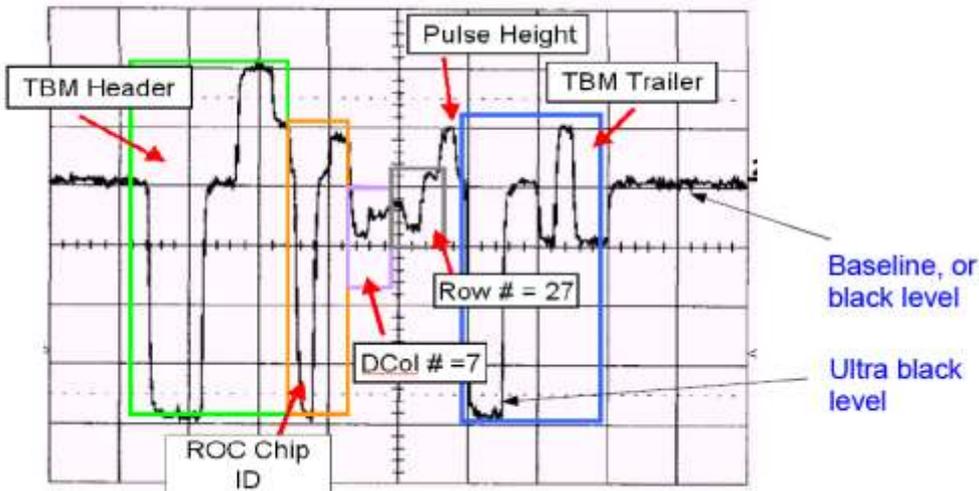


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Commissioning Phase II – Address Levels Calibration



The analog signal from the TBM

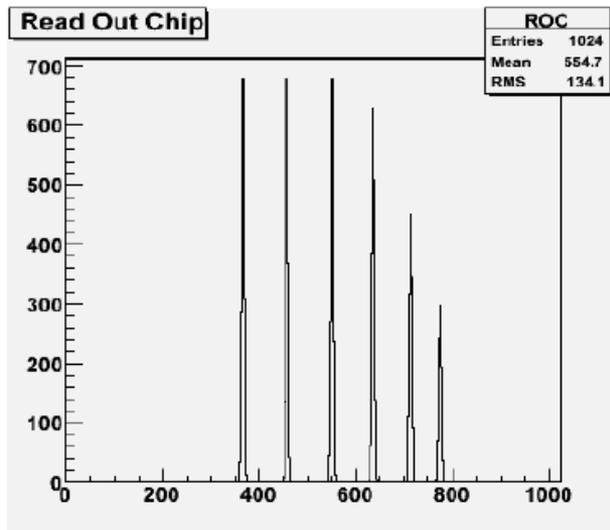
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Poor separation: rms is >5 ADC

